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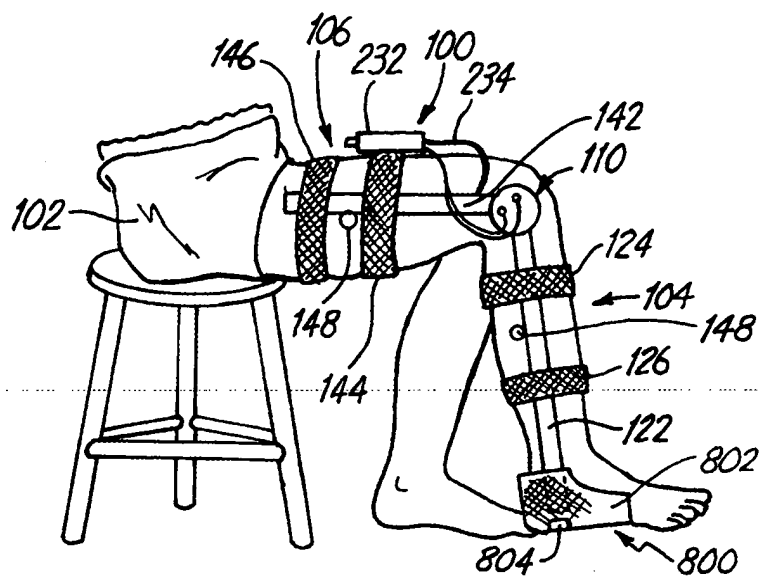


FIG. 1

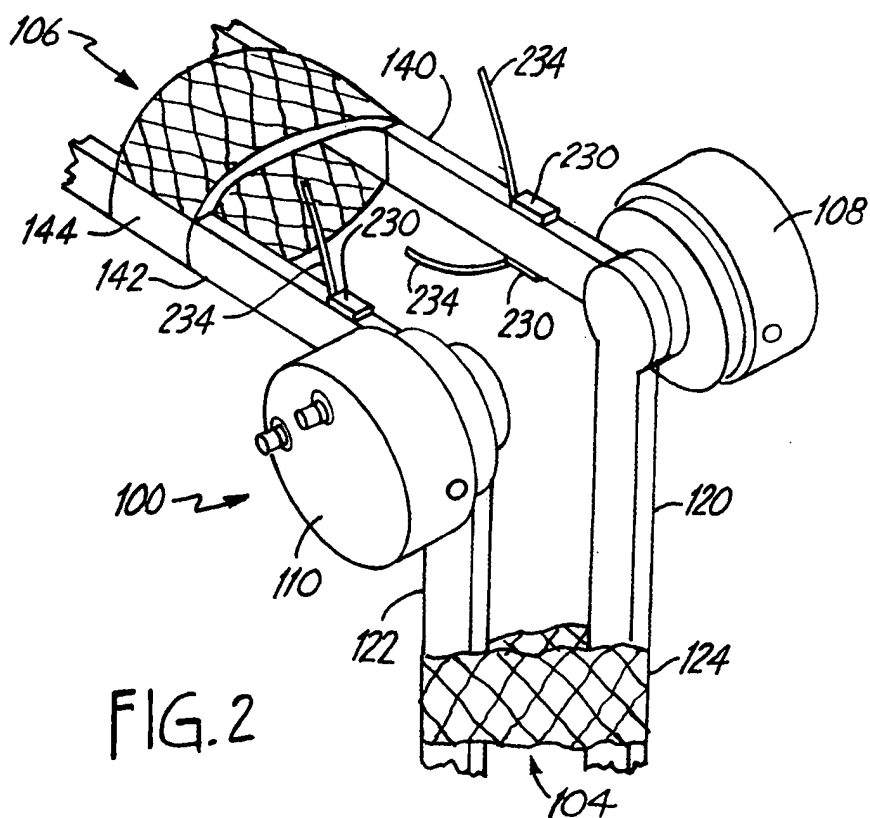
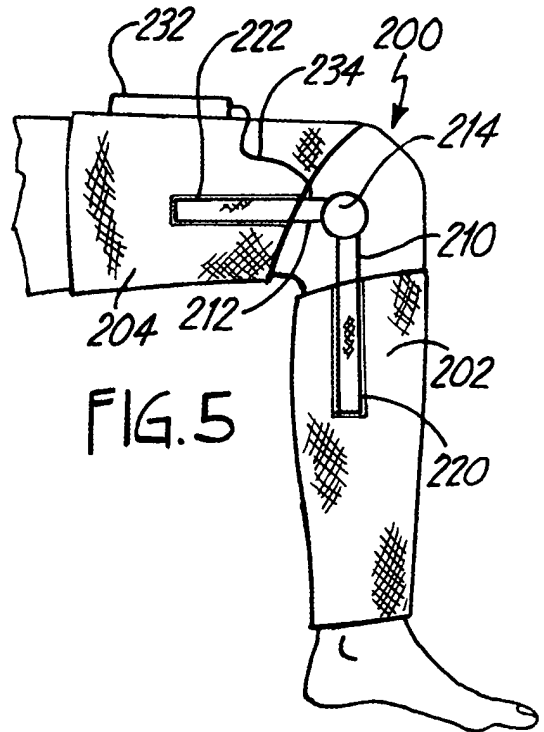
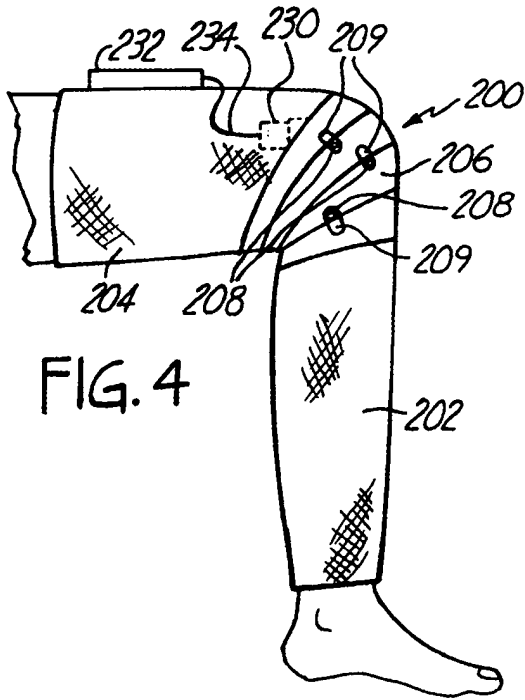
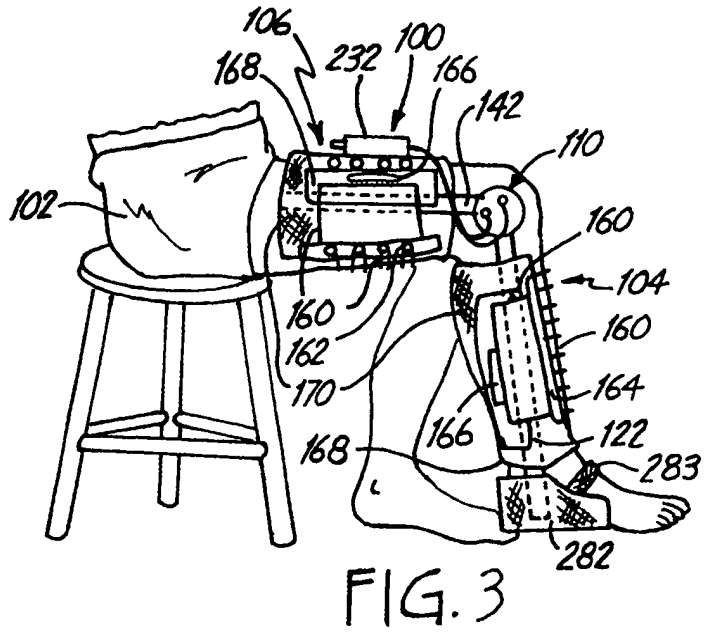


FIG. 2



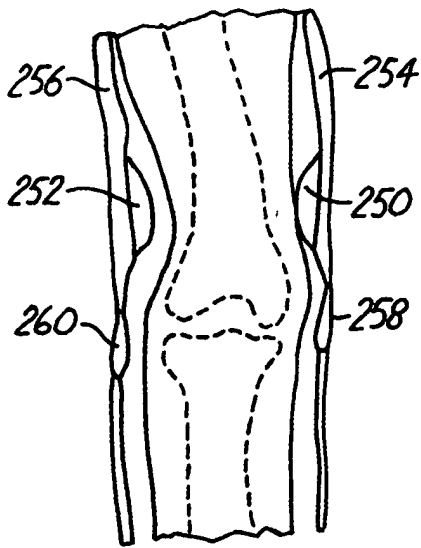


FIG. 6

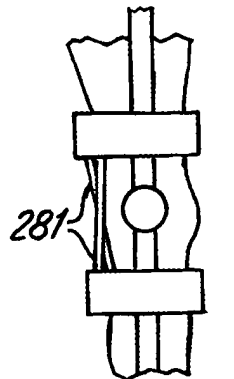


FIG. 12

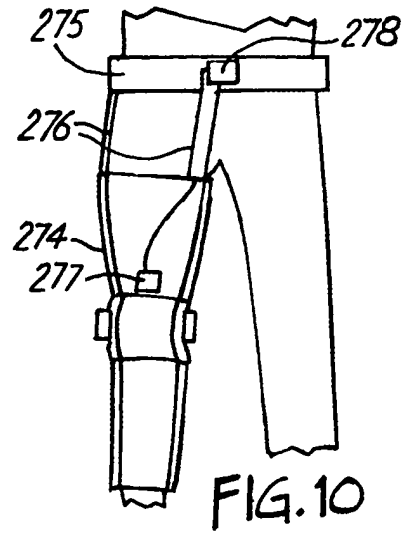


FIG. 10

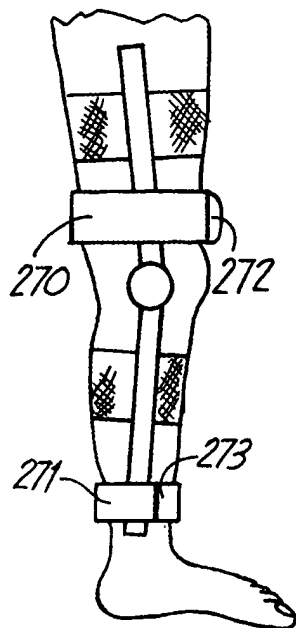


FIG. 7

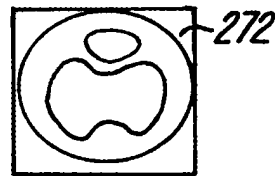


FIG. 8

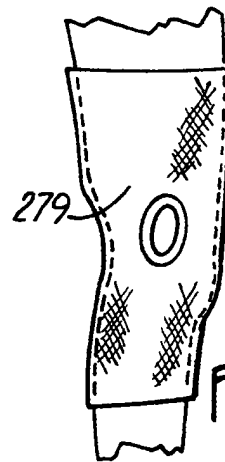


FIG. 11A



FIG. 9

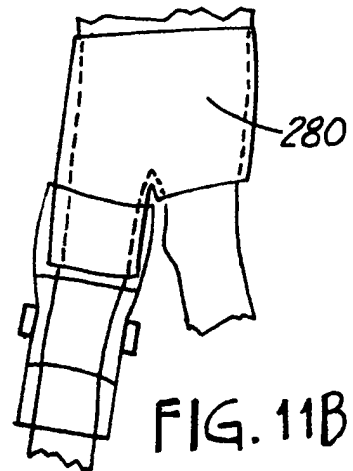


FIG. 11B

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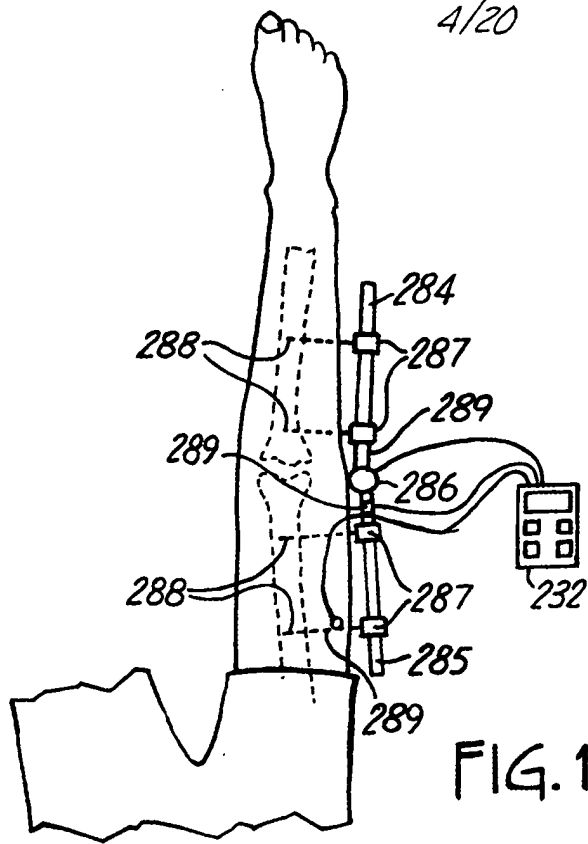


FIG. 13

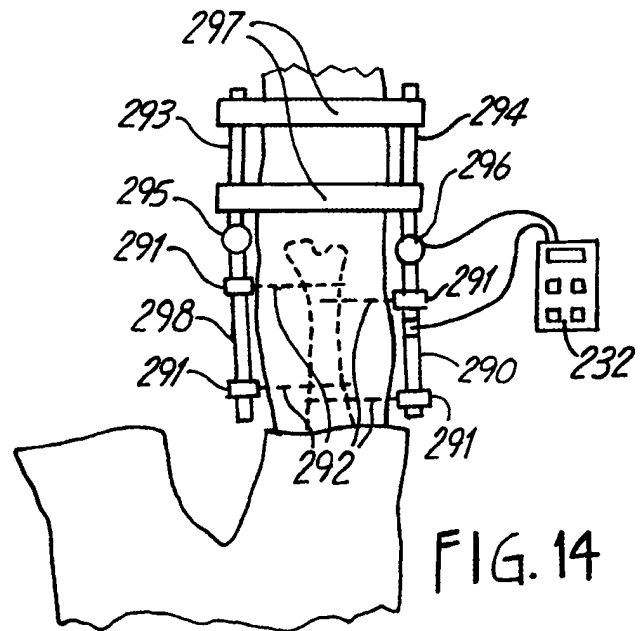
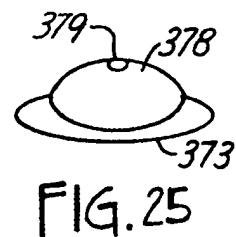
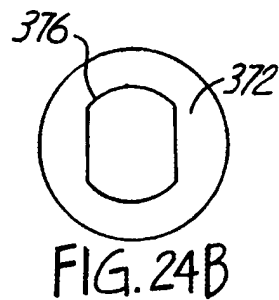
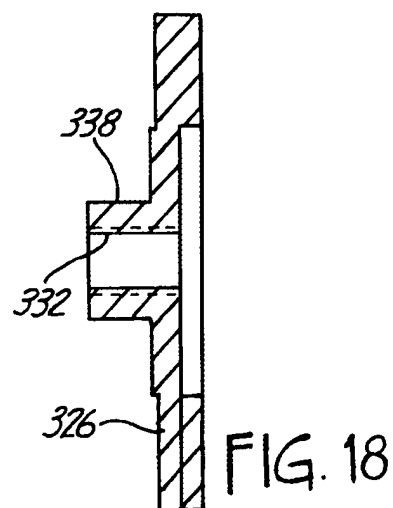
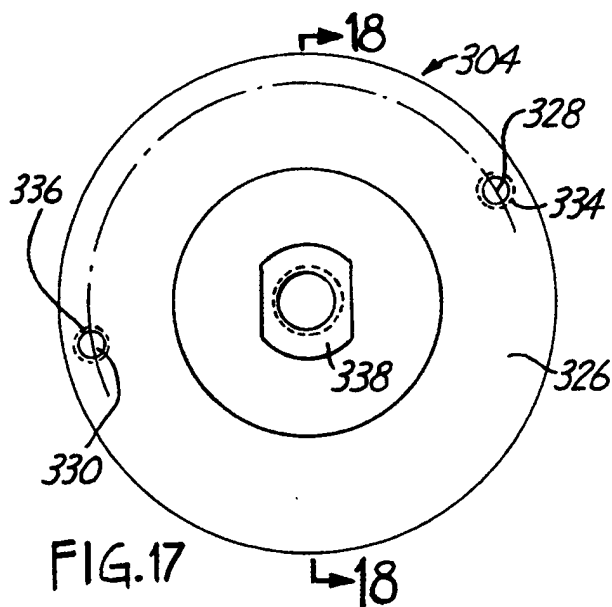
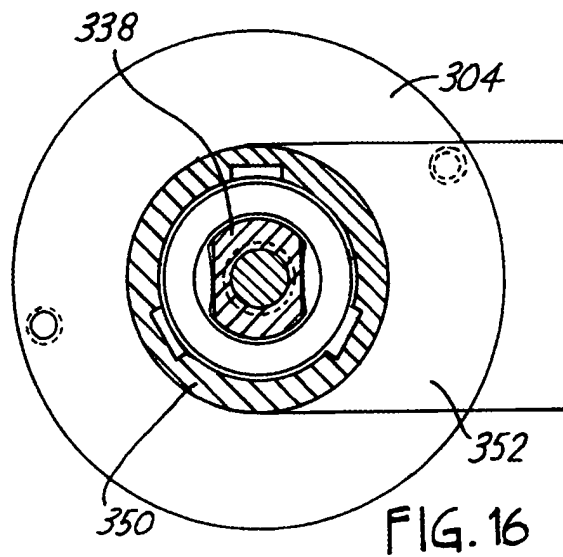
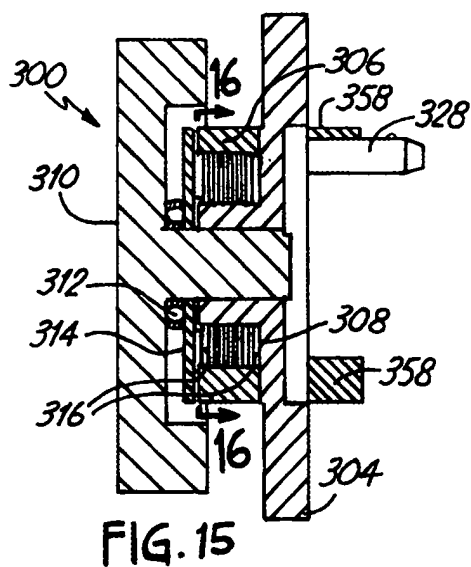
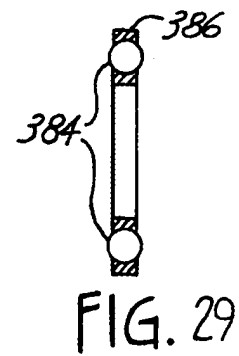
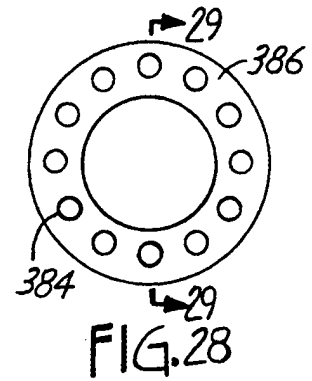
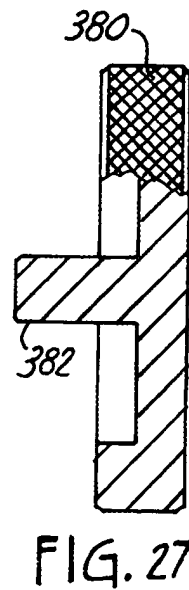
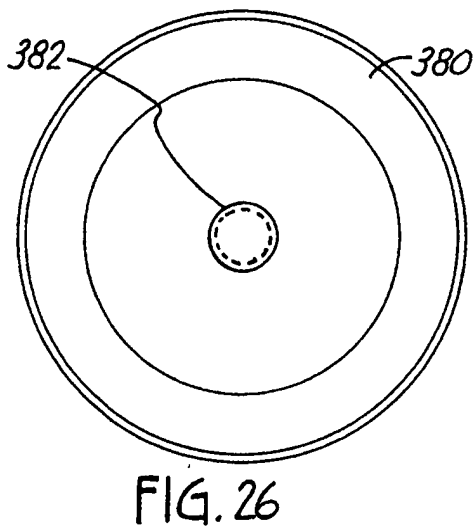
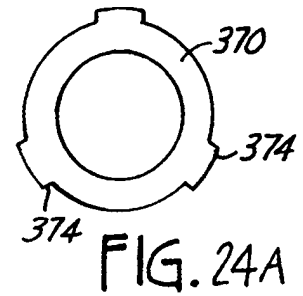
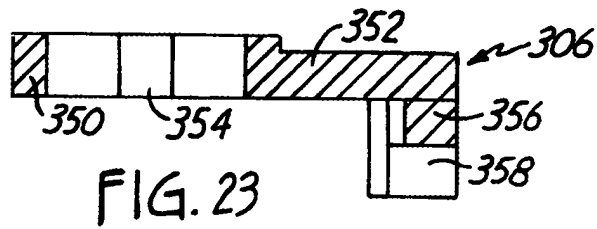
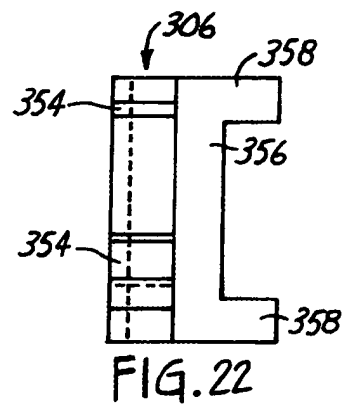
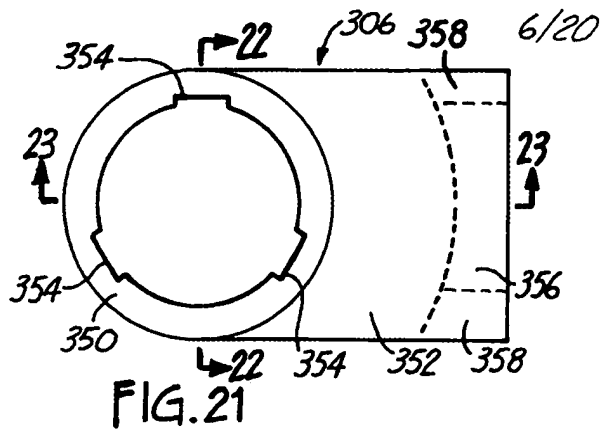


FIG. 14





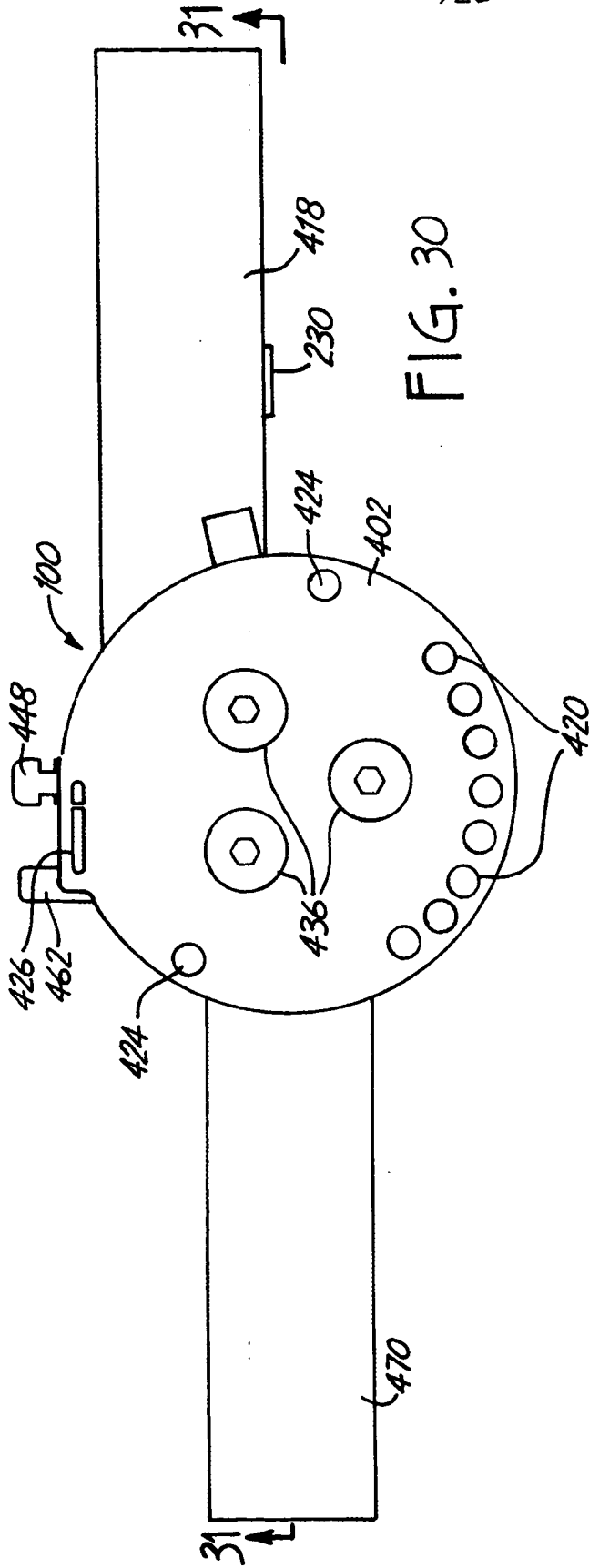


FIG. 30

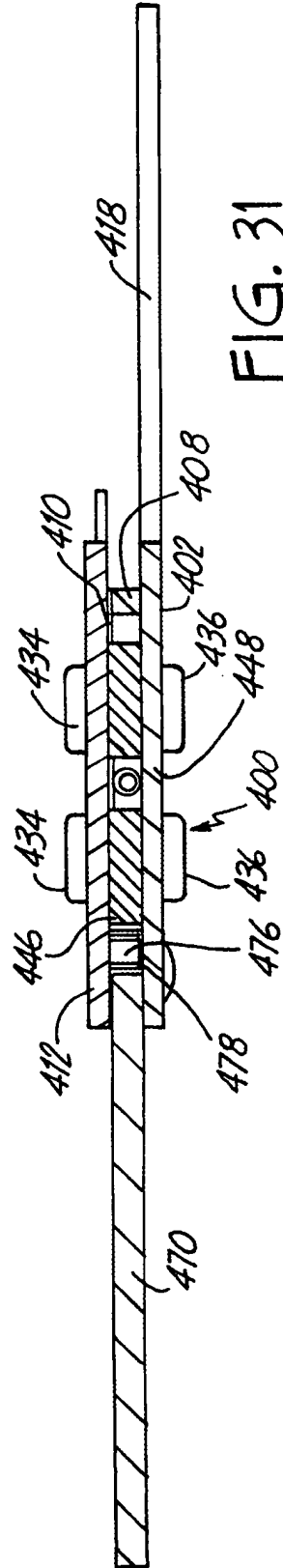
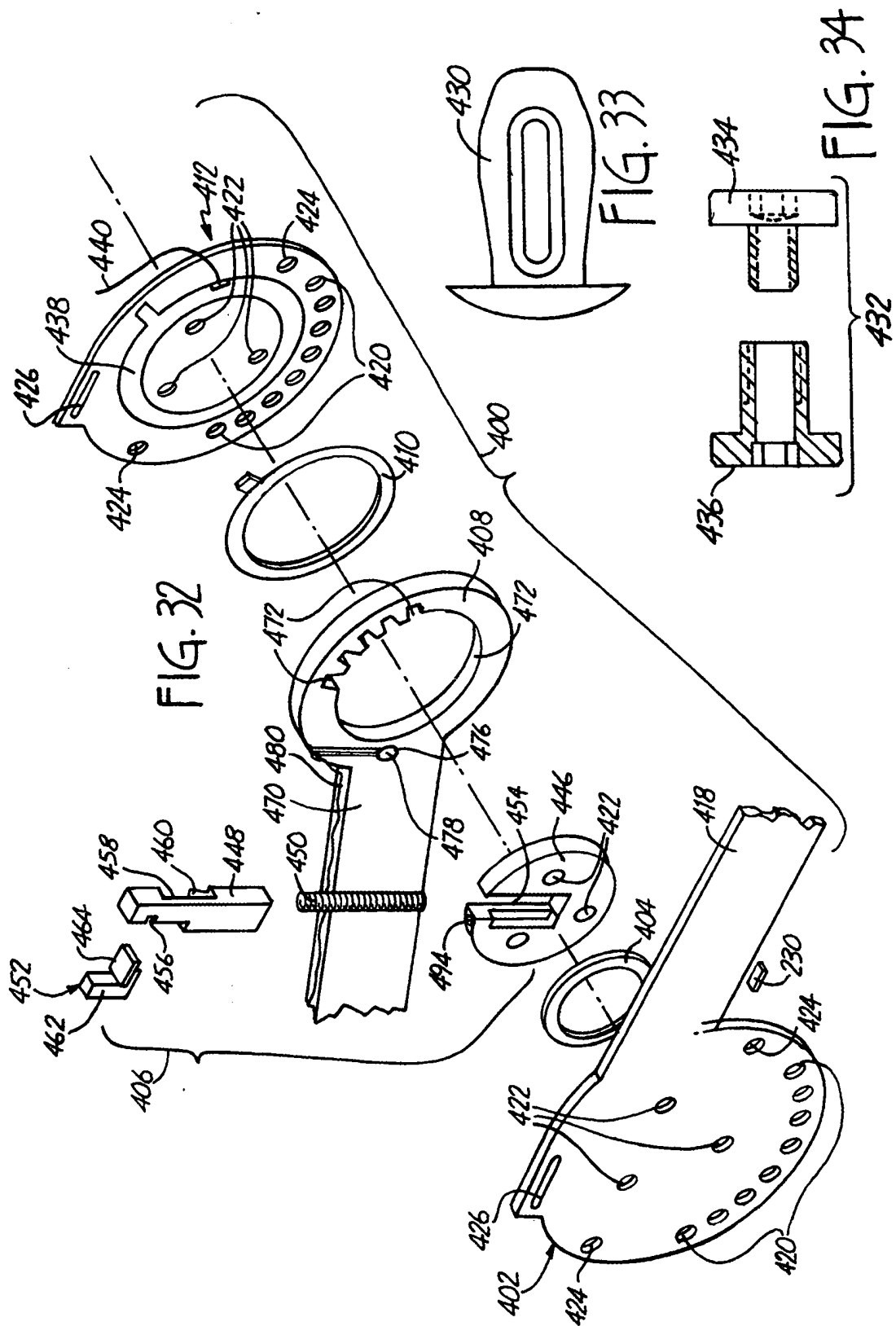


FIG. 31



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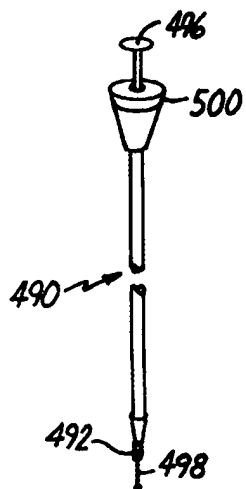


FIG. 35

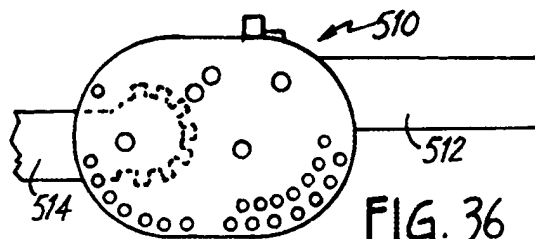


FIG. 36

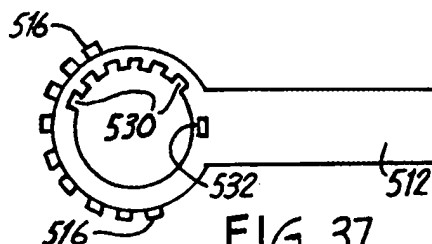


FIG. 37

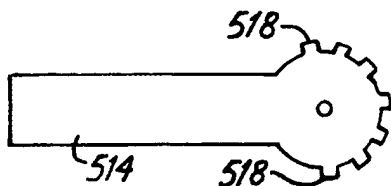


FIG. 38

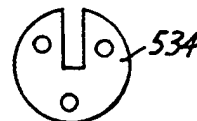


FIG. 39

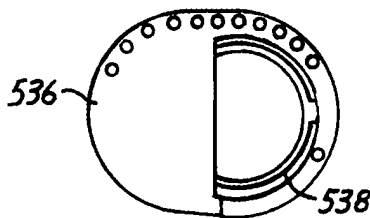


FIG. 40

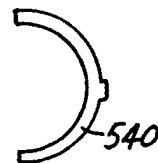


FIG. 41

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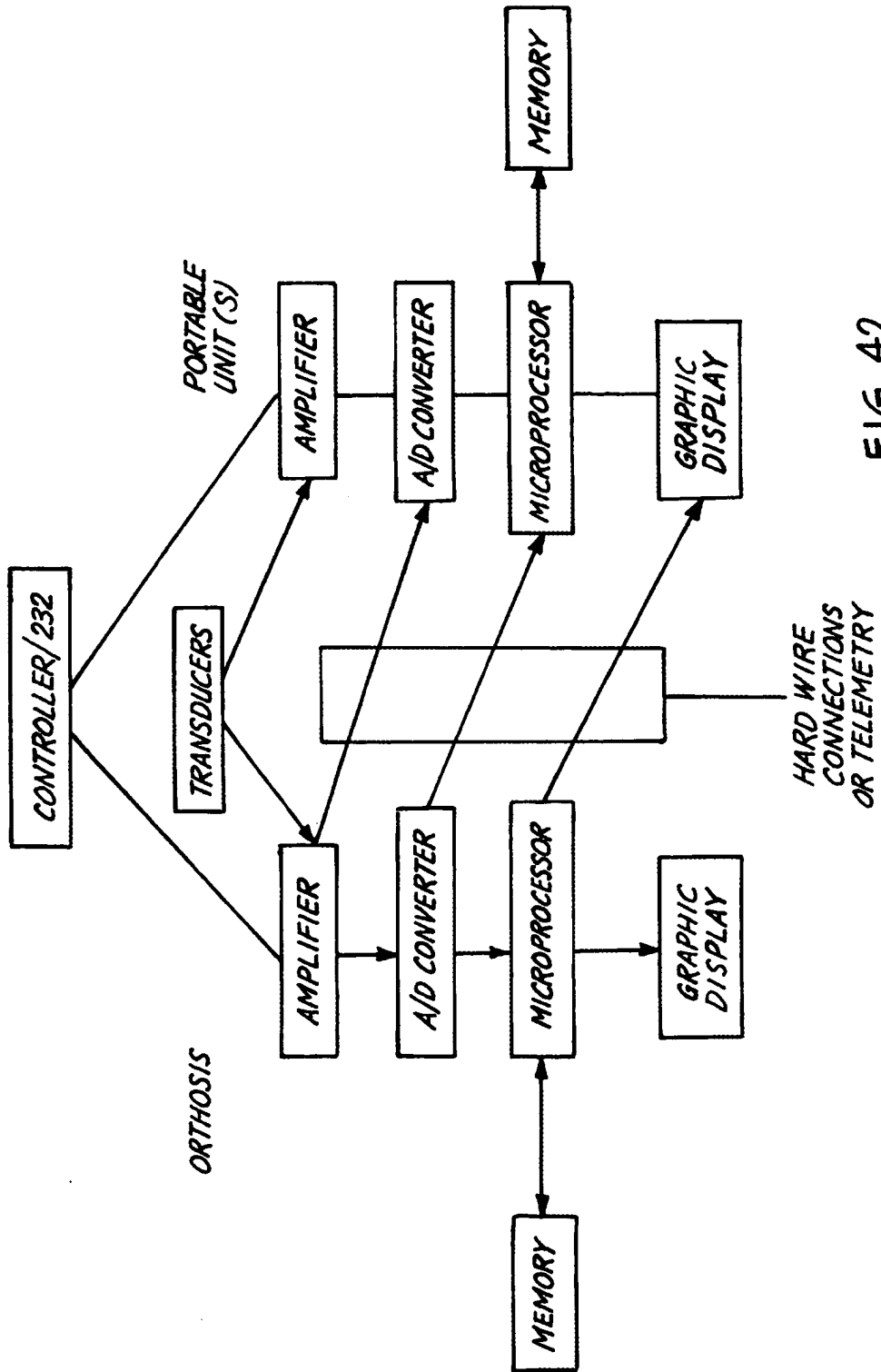
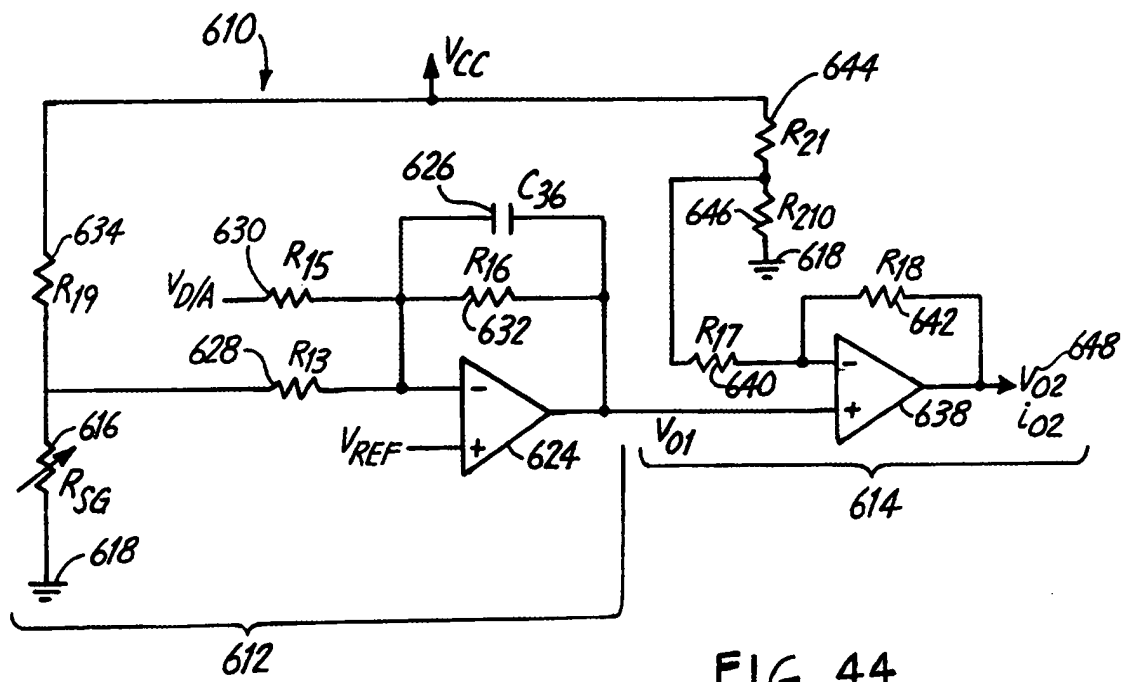
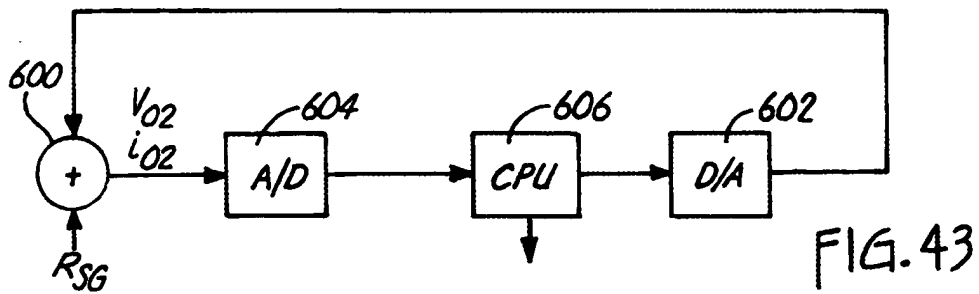


FIG. 42



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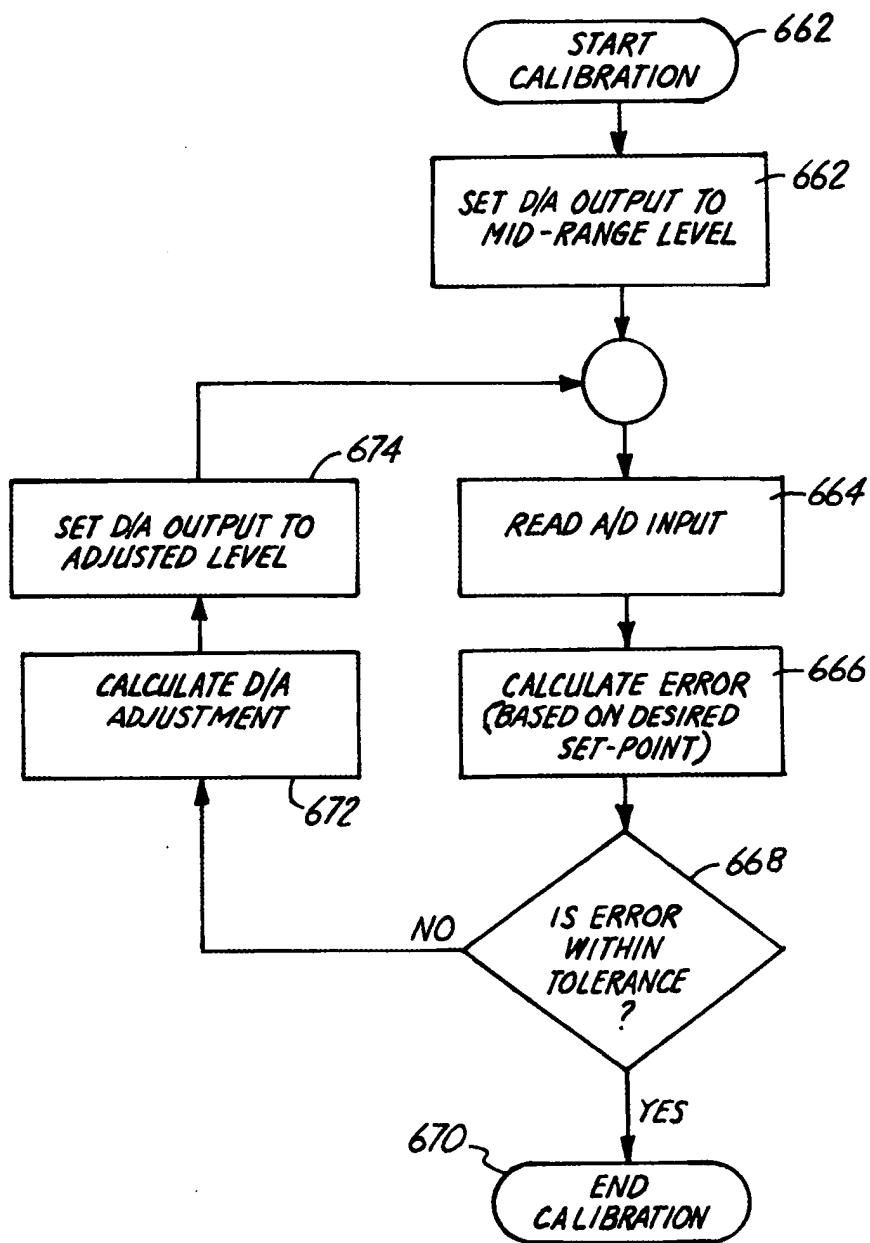


FIG. 45

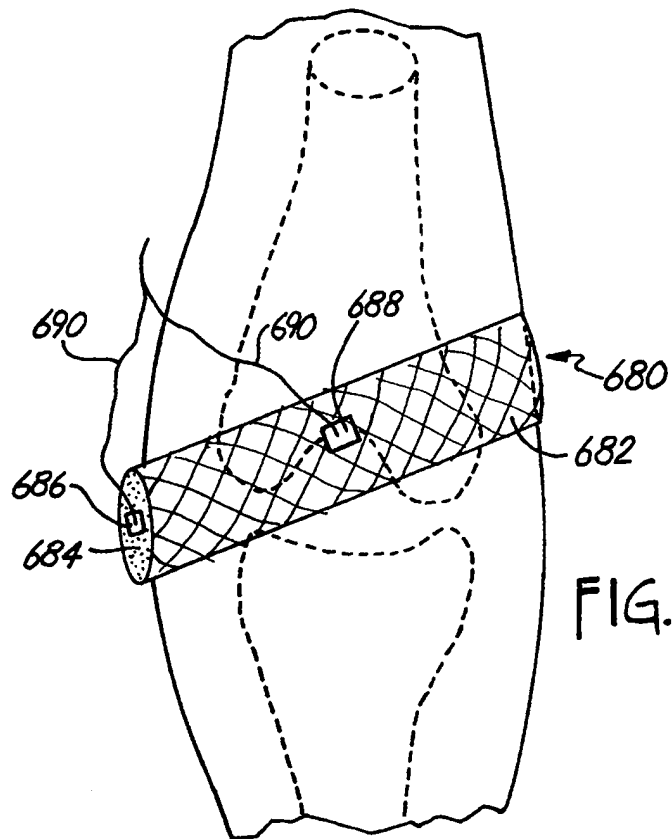


FIG. 46

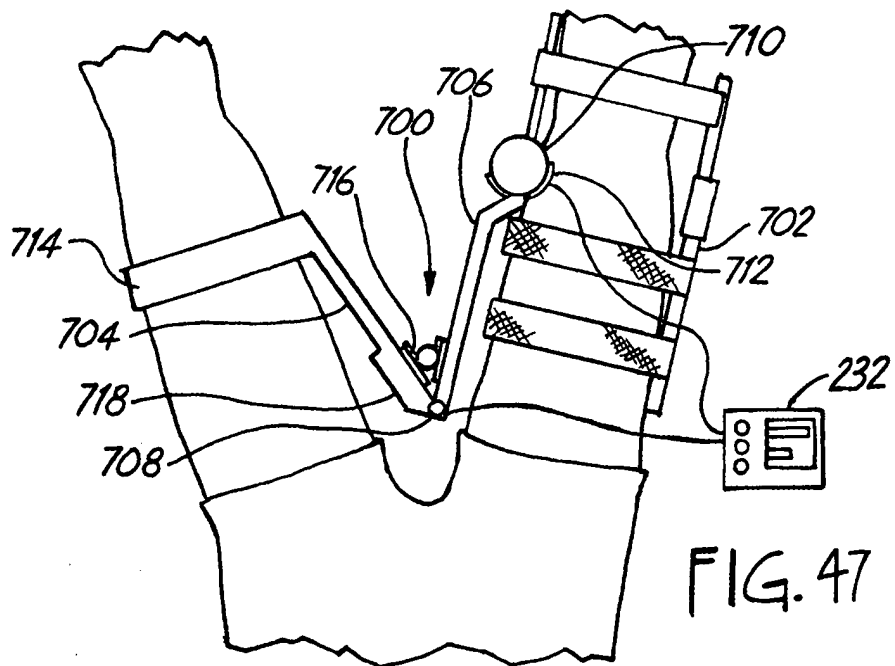


FIG. 47

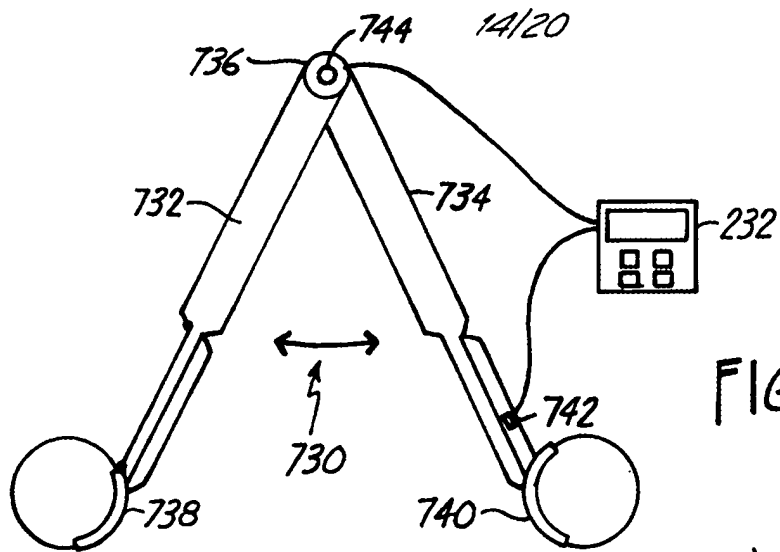


FIG. 48

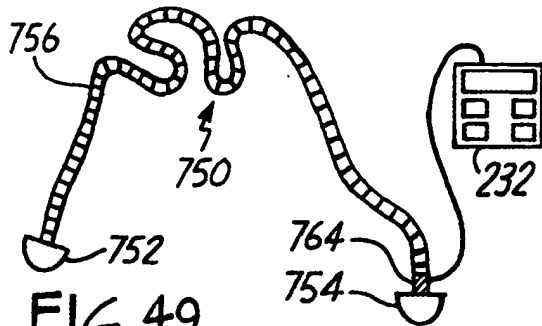


FIG. 49

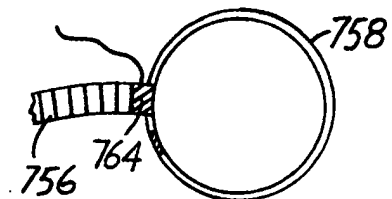


FIG. 50A

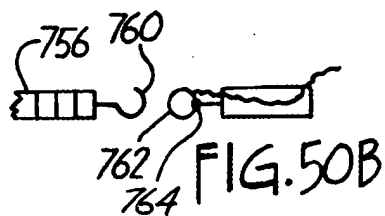


FIG. 50B

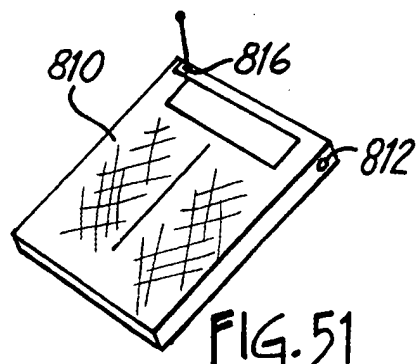
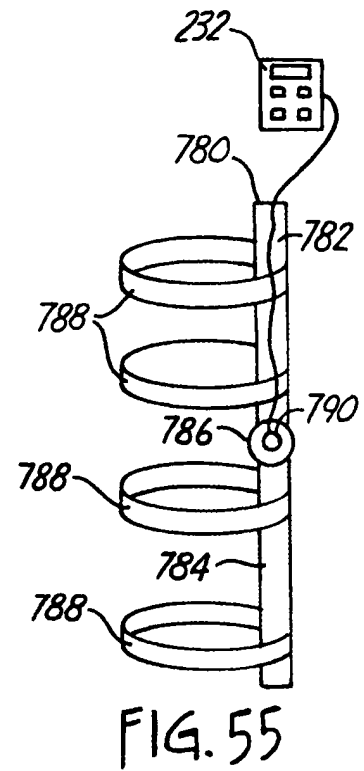
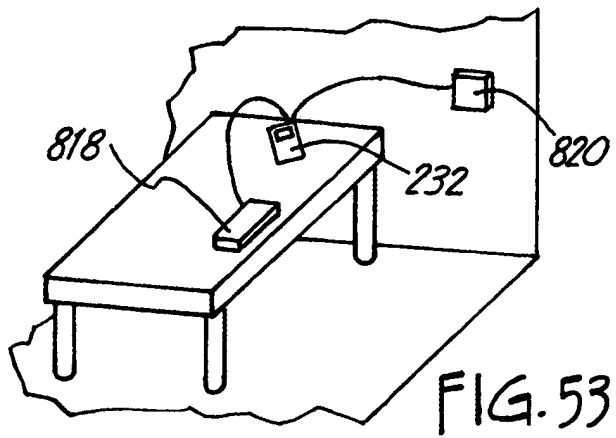
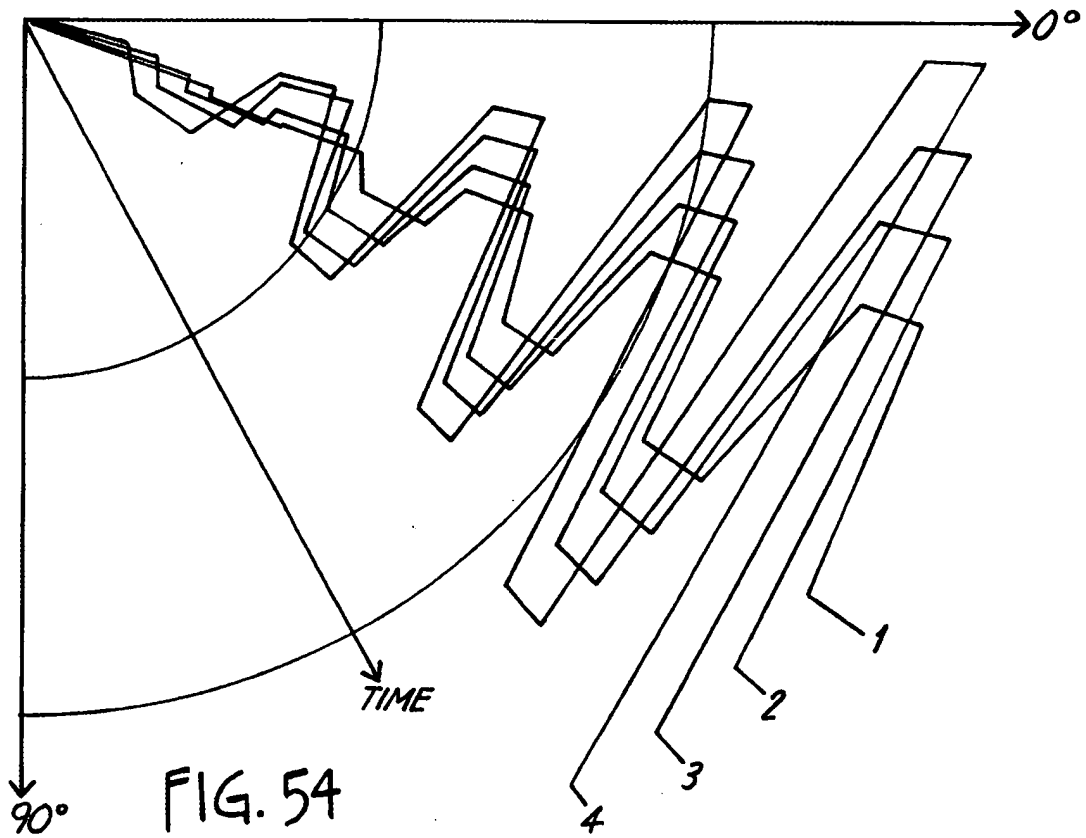


FIG. 51



FIG. 52



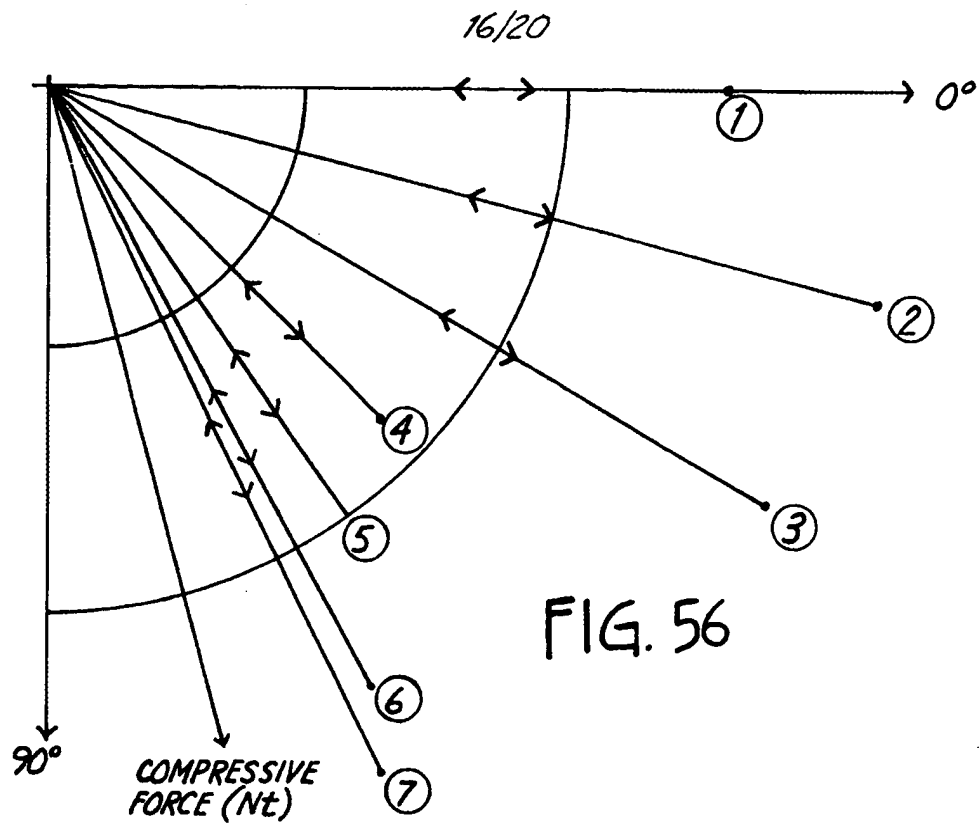


FIG. 56

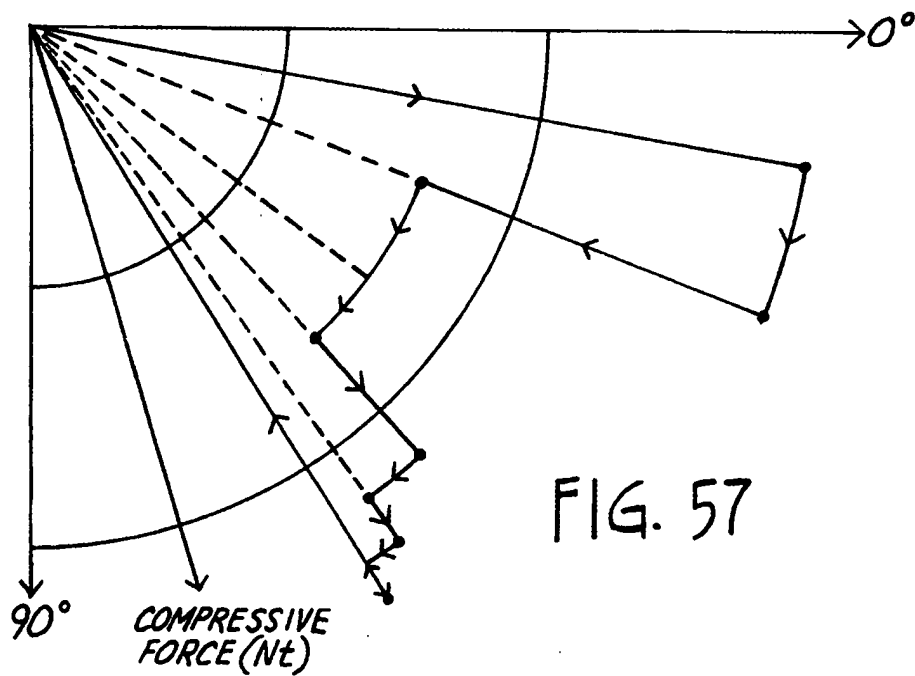


FIG. 57

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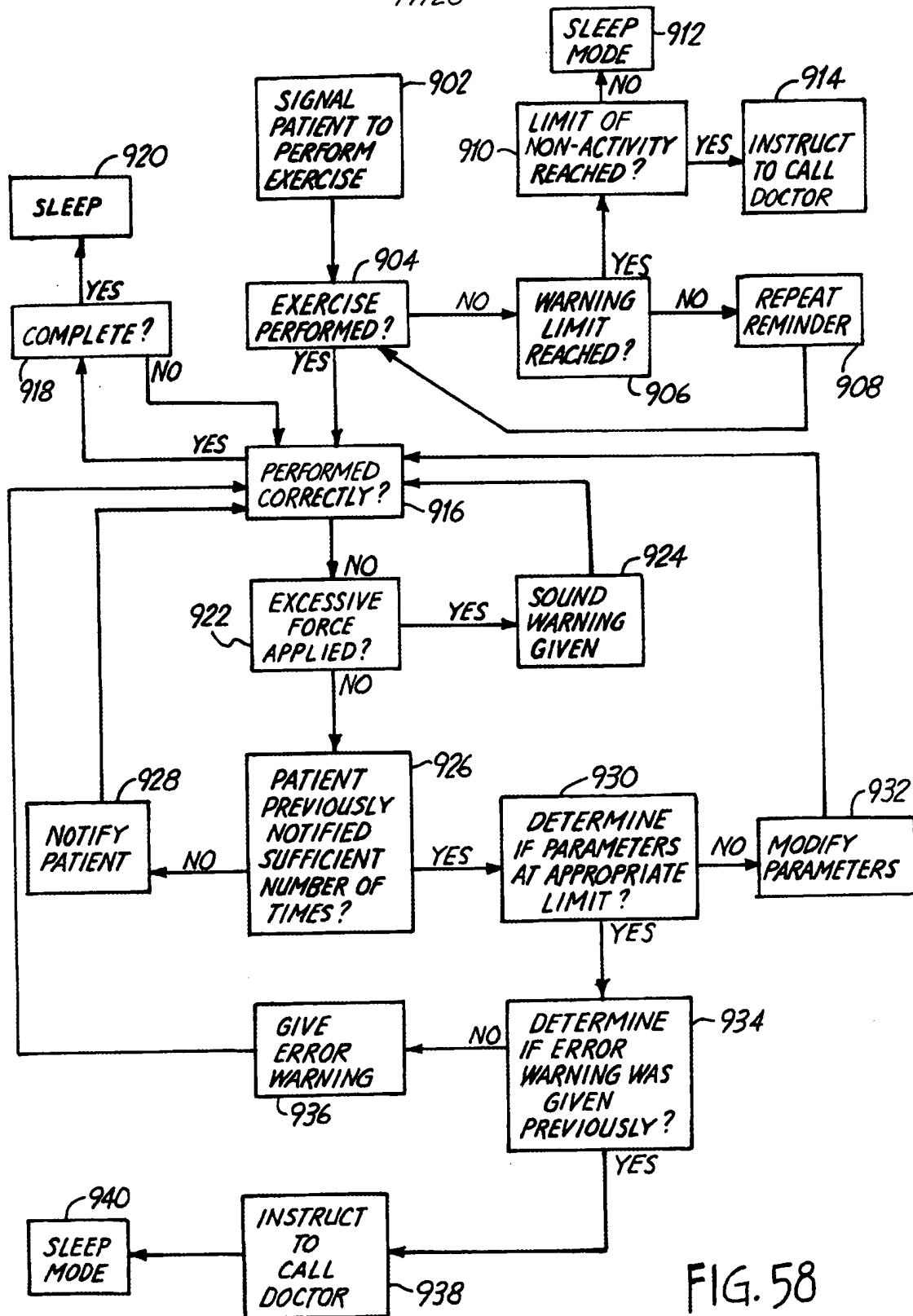


FIG. 58

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EDIT PHASE INFORMATION					
	PHASE 1	PHASE 2	PHASE 3	PHASE 4	PHASE 5
PHASE LENGTH	28	0	0	0	0
ISOMETRICS	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
RANGE OF MOTION	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
PROPRIOCEPTION	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
ISOTONICS	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>
<div>ISEM, ROM, PROP</div> <div>OK</div> <div>CANCEL</div> <div>RESET</div>					

FIG. 59

EDIT TIME PARAMETERS FOR EXERCISES	
CURRENT PHASE = PHASE 1	
PHASE LENGTH	28
REST TIME BETWEEN SETS	4
REST TIME BETWEEN DAYS	10
NUMBER OF SESSIONS PER DAY	3
<div>OK</div> <div>CANCEL</div> <div>RESET</div>	

FIG. 60

EDIT ISOMETRIC EXERCISE PARAMETERS	
CURRENT PHASE = PHASE 1	
EXERCISE SHAPE	2
<div>1 </div> <div>2 </div> <div>3 </div> <div>4 </div>	
CYCLE LENGTH (SECONDS)	10
NUMBER OF CYCLES/REP	3
NUMBER OF ISO REPS/ANG	5
NUMBER OF ANGLES/SET	3
ANGLE VALUES (DEGREES)	<div>1 15</div> <div>2 45</div> <div>3 75</div>
<div>OK</div> <div>CANCEL</div> <div>RESET</div>	

FIG. 61

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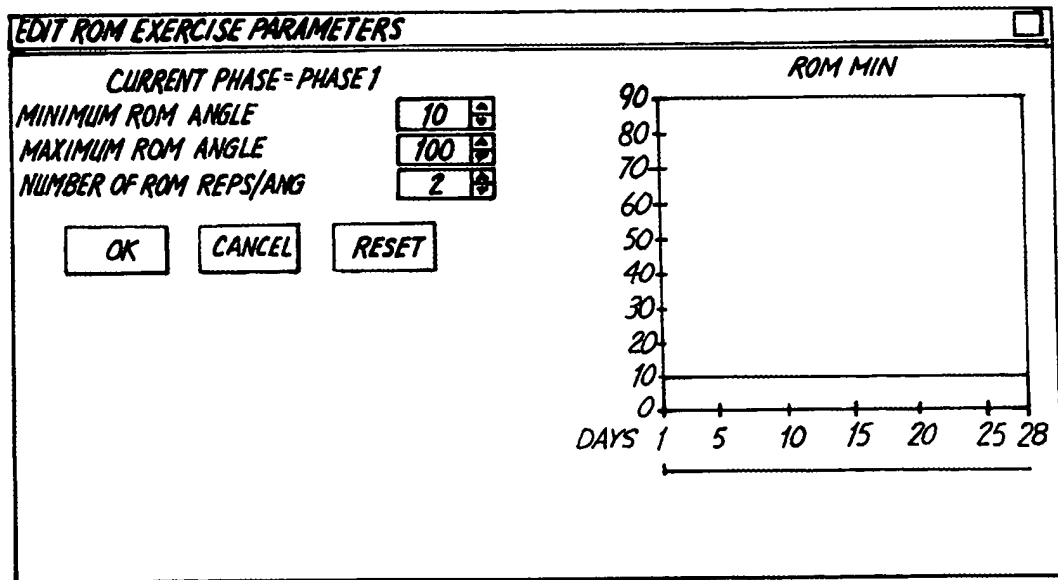


FIG. 62

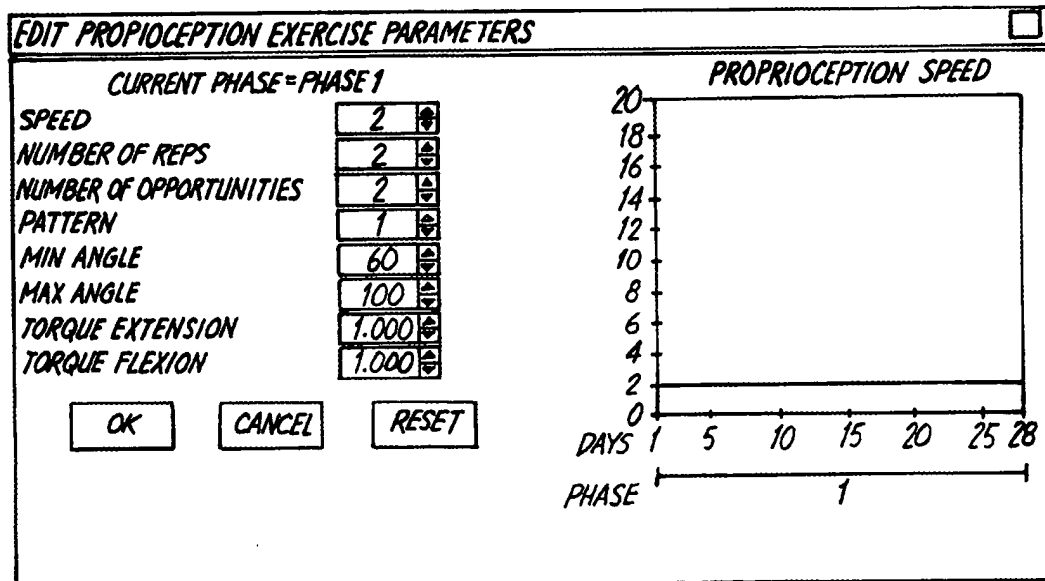



FIG. 63

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EDIT ISOMETRIC EXERCISE SHAPE PARAMETERS

EXERCISE SHAPE PARAMETERS FOR ANGLE 1



ANGLE 15 DEGREES
EXTENSION TORQUE 5.000%
FLEXION TORQUE 5.000%

TOTAL CYCLE LENGTH 48 SECONDS
EXTENSION HOLD TIME 10
FLEXION HOLD TIME 10
BREAK TIME 10
RAMP TIME 2

OK CANCEL RESET

FIG. 64

PLOT TYPE

SELECT PLOT TYPE

☒ ISOMETRIC RAW DATA
☐ ISOMETRIC COMPLIANCE
☐ ROM RAW DATA
☐ ROM MIN/MAX

OK HELP CANCEL

FIG. 65

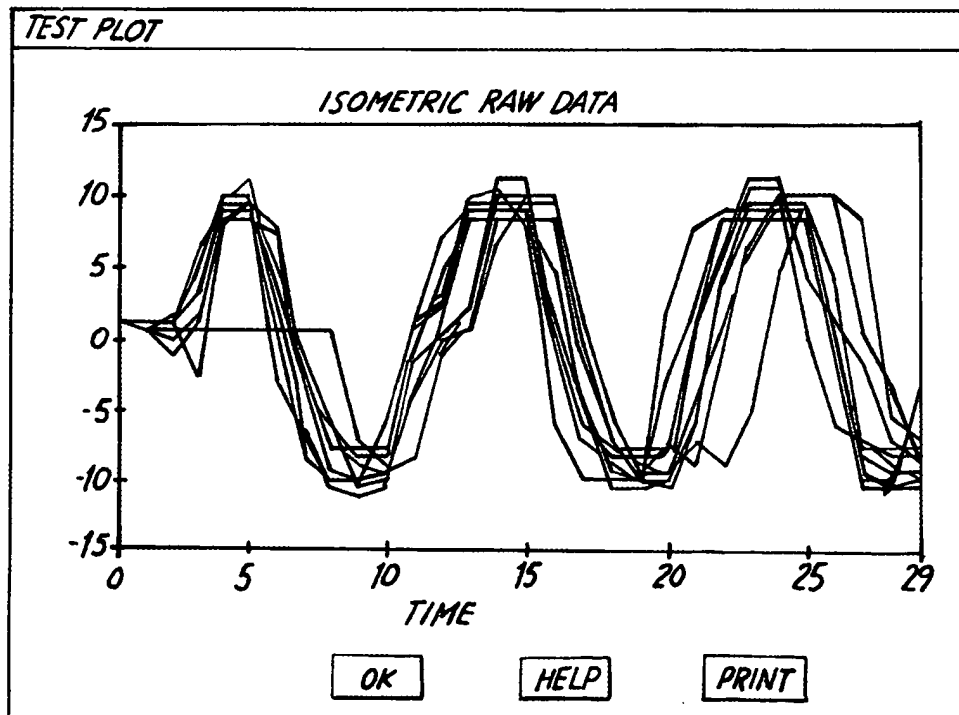


FIG. 66